

Riemannian holonomy and algebraic geometry

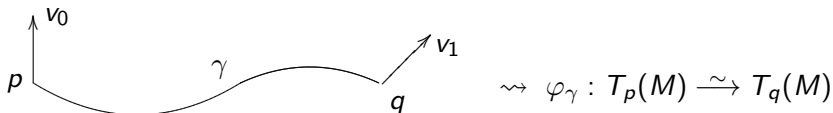
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Parallel transport

(M, g) Riemannian manifold \rightsquigarrow parallel transport:



with $\varphi_\gamma \circ \varphi_\delta = \varphi_{\delta\gamma}$.

Idea : $\gamma : [0, 1] \rightarrow M$, we look for $t \mapsto v(t) \in T_{\gamma(t)}(M)$

- If $M = \mathbb{R}^n$ (euclidean), one imposes $\dot{v}(t) = 0$;
- If $M \subset \mathbb{R}^n$, one imposes $\dot{v}(t) \perp T_{\gamma(t)}(M)$;

linear first order ODE, unique solution with $v(0) = v_0$.

In particular, $\varphi : \{\text{loops at } p\} \longrightarrow O(T_p(M))$

Image = H_p = holonomy (sub-)group at p

- independent of p up to conjugacy (M connected).

For simplicity, we assume M **simply connected** and **compact**.

$\Rightarrow H_p$ compact, connected Lie subgroup of $SO(T_p(M))$
(Borel-Lichnerowicz)

Theorem (de Rham)

$$T_p(M) = \bigoplus_i V_i \text{ stable under } H_p \Rightarrow M \cong \prod_i M_i \text{ et } H_p \cong \prod_i H_{p_i}.$$

We are reduced to **irreducible** manifolds, i.e. with irreducible holonomy representation.

We first exclude a well-known class of manifolds, the **symmetric spaces**: G/H , with G compact Lie group, $H = \text{Fix}(\sigma)^\circ$, σ involution of G . Complete list (E. Cartan), $H_p = H$.

Berger's theorem

Theorem (Berger)

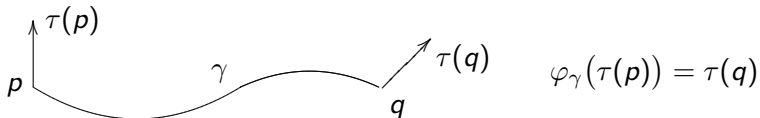
M irreducible ($\pi_1(M) = 0$), non symmetric. Then $H =$

H	$\dim(M)$	<i>metric</i>
$SO(n)$	n	generic
$U(m)$	$2m$	Kähler
$SU(m)$ ($m \geq 3$)	$2m$	Calabi-Yau
$Sp(r)$	$4r$	hyperkähler
$Sp(r)Sp(1)$ ($r \geq 2$)	$4r$	quaternion-Kähler
G_2	7	
$Spin(7)$	8	

Holonomy principle

WHAT IS HOLONOMY GOOD FOR?

A vector field (more generally, a tensor field) τ is **parallel** if



for every path γ from p to q .

Holonomy principle

Evaluation at p gives a bijective correspondence between:

- parallel tensor fields;
- tensors on $T_p(M)$ invariant under H_p .

Examples: SO, U

Hence : fixing $H \iff$ imposing certain parallel tensor fields.

(small holonomy \Rightarrow special manifold)

$$SU(m) \subset U(m) \subset SO(2m), Sp(r) \subset SU(2r), Sp(r) \subset Sp(1)Sp(r)$$

Examples

- $H = SO(n) \iff$ no parallel tensor fields
(except g and dv_g): generic metric.
- $H \subset U(m) \subset SO(2m)$
 - $\iff H$ commutes with endomorphism $v \mapsto iv$ of $\mathbb{R}^{2m} \cong \mathbb{C}^m$
 - \iff **parallel** endomorphism J of $T(M)$, $J^2 = -I$
 - $\iff M$ has a **Kähler** complex structure J .

$H \subset SU(m) \iff H \subset U(m)$ and H preserves the \mathbb{C} -multi-linear alternating m -form $\det : \mathbb{C}^m \rightarrow \mathbb{C}$

$\iff M$ Kähler + holomorphic **parallel** m -form $\omega \neq 0$
(locally, $\omega = f(z) dz_1 \wedge \dots \wedge dz_m$)

Theorem (Yau)

M complex manifold, $\dim_{\mathbb{C}}(M) = m$.

\Updownarrow M admits a Kähler metric with holonomy $\subset SU(m)$;
 \Downarrow M Kählerian, \exists holomorphic m -form everywhere $\neq 0$.

\Rightarrow many examples: hypersurfaces of degree $n + 1$ in \mathbb{P}^n , etc.

$Sp(r) := U(r, \mathbb{H}) =$ subgroup of $GL(r, \mathbb{H})$ preserving the hermitian form $\psi(x, y) = \sum x_i \bar{y}_i$.

2 ways of looking at quaternions:

- “Hamilton”: $\mathbb{H} = \mathbb{R} + \mathbb{R}i + \mathbb{R}j + \mathbb{R}k$, $\mathbb{H}^r \cong \mathbb{R}^{4r}$.

$Sp(r) =$ subgroup of $O(\mathbb{R}^{4r})$ commuting with i, j, k .

$H \subset Sp(r) \iff$ parallel complex structures I, J, K ,
actually a sphere \mathbb{S}^2 :

$$\mathbb{S}^2 = \{aI + bJ + cK, a^2 + b^2 + c^2 = 1\}.$$

We say that M est **hyperkähler**.

$Sp(r)$ – holomorphic symplectic point of view

- “Cayley”: $\mathbb{C} = \mathbb{R} + \mathbb{R}i$, $\mathbb{H} = \mathbb{C}(j)$ with $jz = \bar{z}j$; $\mathbb{H}^r \cong \mathbb{C}^{2r}$.
 $\psi = h + \varphi j$ with h \mathbb{C} -hermitian and φ \mathbb{C} -bilinear alternating.

Thus $Sp(r) = U(2r, \mathbb{C}) \cap Sp(2r, \mathbb{C})$.

$$H = Sp(r) \iff \begin{cases} \text{complex Kähler structure +} \\ \text{parallel holomorphic symplectic 2-form } \varphi, \\ \text{unique up to a scalar} \end{cases}$$

Theorem

M kählerian with holomorphic symplectic 2-form $\varphi \Rightarrow$

M admits a hyperkähler metric.

Proof: φ^r $(2r)$ -form $\neq 0 \Rightarrow M$ admits a Kähler metric with holonomy $\subset SU(m)$ (Yau); for such a metric, every holomorphic tensor field is parallel (Bochner).

Examples

① $r = 1$: $Sp(1) = SU(2)$, $M =$ complex surface (compact) with holomorphic 2-form everywhere $\neq 0 \stackrel{\text{def}}{=} \text{K3 surface}$.

② $r > 1$? Idea: S^r admits symplectic forms, in fact too many:

$$\sigma = \lambda_1 p_1^* \varphi + \dots + \lambda_r p_r^* \varphi, \quad \text{with } \lambda_1, \dots, \lambda_r \in \mathbb{C}^* .$$

To get unicity, try to impose $\lambda_1 = \dots = \lambda_r$, i.e.:

σ comes from $S^{(r)} := S^r / \mathfrak{S}_r$.

$S^{(r)}$ is singular, but admits a **resolution** $S^{[r]}$, the **Hilbert scheme** (or Douady space).

σ symplectic form on $S^{[r]} \Rightarrow S^{[r]}$ hyperkähler.

Examples (continued)

- 3 Analogous construction starting from a 2-dim'l complex torus
 \rightsquigarrow generalized Kummer varieties K_r .
- 4 2 isolated examples (O'Grady), of dimension 6 and 10.

No other example known! (up to deformation)

$Sp(1)Sp(r)$

$Sp(r) = U(r, \mathbb{H})$ commutes with homotheties, in particular with

$$\mathbb{H}_1^\times = \{\text{quaternions with norm } 1\} \cong Sp(1),$$

hence a group $Sp(1)Sp(r) \subset SO(4r)$, $\not\subset U(2r)$.

It preserves the sphere

$$\mathbb{S}^2 = \{aI + bJ + cK, a^2 + b^2 + c^2 = 1\} \subset \text{End}(\mathbb{R}^{4r}).$$

For M with holonomy $Sp(1)Sp(r)$ (“quaternion-Kähler”), get sphere $\mathbb{S}_p^2 \subset \text{End}(T_p(M))$ at each $p \in M$.

The union of these spheres is the **twistor space** $t : Z \rightarrow M$.

Theorem (Salamon)

Z has a natural complex structure, such that $t^{-1}(m) \cong \mathbb{P}^1 \quad \forall m$,
and a holomorphic contact structure.

Contact and complex structures on Z

contact structure = odd-dim'l analogue of symplectic structure
= sub-bundle of hyperplanes $H \subset T(Z)$,
defined locally by 1-form η such that $d\eta|_H$ symplectic.

Idea of the construction

For $(p, J) \in Z$, $T_{(p,J)}(Z) = T_p(M) \oplus T_J(\mathbb{S}^2)$

- complex structure J on $T_p(M)$, standard on $T_J(\mathbb{S}^2)$
- contact structure: $H_{(p,J)} = T_p(M) \subset T_{(p,J)}(Z)$. ■

Two cases, according to the sign of the scalar curvature.

Negative case: Z not Kähler, no example known.

Contact projective manifolds

Positive case : Z is a **projective** manifold, even **Fano**.

(i.e.: K_Z^{-N} has many sections for $N \gg 0$).

Examples of contact projective manifolds

- 1 $\mathbb{P}T^*(X)$ for every projective manifold X ;
- 2 \mathfrak{g} simple Lie algebra; $\mathcal{O}_{min} \subset \mathbb{P}(\mathfrak{g})$ unique closed adjoint orbit.
(example: rank 1 matrices in $\mathbb{P}(\mathfrak{sl}_r)$.)

Conjectures

- 1 These are the only contact projective manifolds.
- 2 Every quaternion-Kähler positive manifold is symmetric.

① \Rightarrow ② : Z Fano $\Rightarrow Z = \mathcal{O}_{min} \Rightarrow M$ symmetric (Wolf space).

Every contact projective manifold is $\mathbb{P}T^*(X)$ or \mathcal{O}_{min} ?

Partial results

Z contact projective manifold, $L := T(Z)/H$

- 1 If Z is **not** Fano, $Z \cong \mathbb{P}T^*(X)$
(Kebekus, Peternell, Sommese, Wiśniewski + Demailly)
- 2 Z Fano **and** L has “enough sections” $\Rightarrow Z \cong \mathcal{O}_{min} \subset \mathbb{P}(\mathfrak{g})$
(AB; note: Z Fano $\Rightarrow L^N$ has many sections for $N \gg 0$)

THE END